

Electrical Technology

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NETWORK DEFINITIONS

LINEAR SYSTEM : A system(network) is linear if (a) the principle of SUPERPOSITION and(b) the principle of PROPORTIONALITY hold.

SUPERPOSITION PRINCIPLE : If for a given network, $\{ e_1(t), r_1(t) \}$ and $\{ e_2(t), r_2(t) \}$ are excitation-response pairs, then if the excitation were $e(t) = e_1(t) + e_2(t)$, the response would be $r(t) = r_1(t) + r_2(t)$.

PROPORTIONALITY PRINCIPLE If for a given network, $e_1(t), r_1(t)$ are excitation-response pairs, then if the excitation were $c_1 e_1(t)$, then response would be $c_1 r_1(t)$. The constant of proportionality is c_1 is preserved by the linear network. In a system if

$$c_1 e_1(t) + c_2 e_2(t) \text{ gives rise to } c_1 r_1(t) + c_2 r_2(t).$$

Then the system is a linear system

PASSIVE SYSTEM A linear network is passive if (a) the energy delivered to the network is non-negative for any arbitrary excitation, and (b) if no voltages or currents appear between any two terminals before an excitation is applied.

NETWORK ANALYSIS (CONTD)

- **RECIPROCAL** A network is said to be **reciprocal** if when the points of excitation and measurement of response are interchanged, the relationship between excitation and response remains the same. This must be true for any choice of points of excitation & response.
- **CAUSAL** A system is causal if its response is non-anticipatory, i.e., if

$$e(t) = 0 \quad t < T$$

$$\text{then } r(t) = 0 \quad t < T$$

in other words, a system is causal if before an excitation is applied at $t = T$, the response is zero for $-\infty < t < T$.

TIME INVARIANT A system is time invariant if $e(t) \rightarrow r(t)$ implies that $e(t \pm T) \rightarrow r(t \pm T)$. From this property we can show that if $e(t)$ at the input gives rise to $r(t)$ at the output then if the input were $e'(t)$ i.e. the derivative of $e(t)$, the response would be $r'(t)$.

This idea is applicable to higher derivatives as well as for the integrals of $e(t)$ and $r(t)$.

IDEAL MODELS AND ELEMENTS

- **AMPLIFIER** : An amplifier scales up the magnitude of the input , i.e., $r(t) = K e(t)$, where K is a constant.
- **DIFFERENTIATOR** : The input signal is differentiated and possibly scaled up or down.
- **INTEGRATOR** The output is the integral of the input.
- **TIME DELAYER** The output is delayed by an amount T , but retains the same wave shape as the input
- **IDEAL ELEMENTS/ ENERGY SOURCES.** Resistor R given in ohms, the Capacitor C ,given in farads , and the Inductor L , expressed in Henrys are the main elements used in networks in addition to current or voltage energy sources. These energy sources could be independent or dependent . The dependent sources could be either voltage controlled or current controlled.

GENERAL CHARACTERISTICS OF SIGNALS

- **PERIODIC OR APERIODIC SIGNAL** A signal is said to be periodic if it can be described by the equation $f(t) = f(t \pm kT)$ where $k = 0, 1, 2, \dots$. Where T is the period of the signal. The sine wave, $\sin t$, is periodic with period $T = 2\pi$. Another example of periodic signal is the Square Wave.
- Signals like pulses (rectangular, triangular) are not periodic because the pulse patterns do not repeat after certain finite interval T .
- For discrete time signal $x(n)$, the condition of periodicity can be written as $x(n + N_0) = x(n)$ where N_0 is sampling period or no of samples after which signals repeat itself.
- A signal which does not repeat itself after a fixed time period or does not repeat at all is aperiodic or non periodic signal.
- **PERIODICITY OF SUM OF TWO PERIODIC SIGNALS**
The sum of two periodic continuous time signals will be periodic if the ratio of their fundamental period is rational.
(A discrete time signal is periodic only if frequency f_0 is rational i.e. in form of two integers)

GENERAL DESCRIPTION OF SIGNALS

- **Time Constant** It refers only to exponential waveforms .It is a useful measure of the decay of an exponential . Consider an exponential waveform described by

$r(t) = K e^{-t/T} u(t)$ from the plot of this function we see that when $t = T$,

$$r(t) = 0.37 r(0)$$

also $r(4T) = 0.02 r(0)$. This shows that the larger the time constant ,the longer it requires for the waveform to reach 37 % of its peak value. In circuit analysis ,the common time constants are the factors RC and RL .

- **RMS Value , D-C Value , Duty Cycle and Crest Factor** are other terms which describe only Periodic Waveforms.

r m s value

- The r.m.s value of an alternating current is given by
- **That steady (d.c) current which when flowing through a given circuit for a given time produces the same heat as produced by the alternating current when flowing through the same circuit for the same time.**
- It is also known as the effective or virtual value of the alternating current. The term EFFECTIVE value is used more extensively.S

GENERAL DESCRIPTION OF SIGNALS (CONTD)

- **RMS Value** The rms or root mean square value of a periodic waveform $e(t)$ is defined

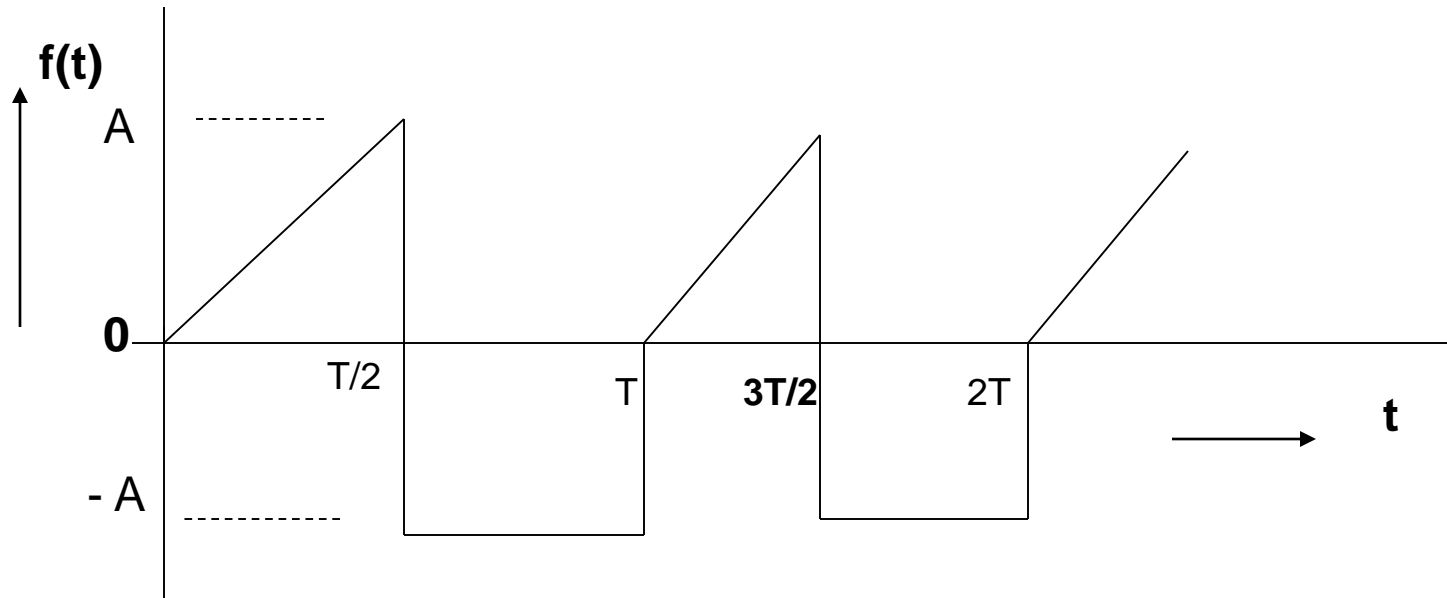
$$e_{\text{rms}} = \left[\frac{1}{T} \int_0^T e^2(t) dt \right]^{1/2} \text{ where } T \text{ is the period. If the}$$

waveform is not periodic, the term rms does not apply.

Show that for a periodic waveform which is triangular in period 0 to T/2 with amplitude increasing from 0 to A v and rectangular in next half period T/2 to T with amplitude - A v during this half period. The rms value works out to be

$$\sqrt{2/3} A v$$

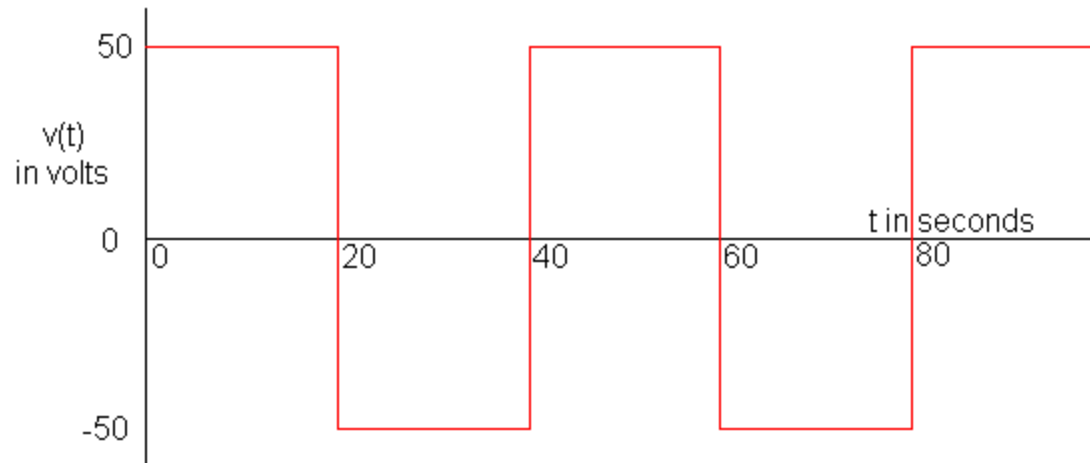
Ex : find rms value of the waveform shown below



Solution

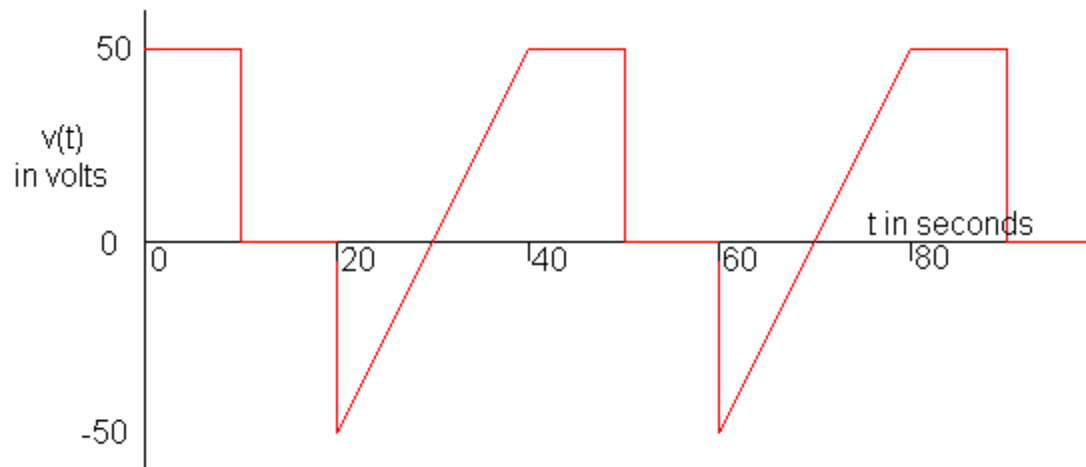
$$\begin{aligned} \bullet E_{\text{rms}} &= \left[\frac{1}{T} \left\{ \int_0^{T/2} (2A t/T)^2 dt + \int_{T/2}^T A^2 dt \right\} \right]^{1/2} \\ &= \left[\frac{1}{T} \left\{ \left(\frac{4A^2}{T^2} \right) \left. \frac{t^3}{3} \right|_0^{T/2} + \left. A^2 t \right|_{T/2}^T \right\} \right]^{1/2} \\ &= A \sqrt{2/3} \end{aligned}$$

- Find rms value of the waveform shown below



$$V_{\text{rms}} = \{[50^2 + (-50)^2]/2\}^{1/2} = \{[2500 + 2500]/2\}^{1/2} = \{2500\}^{1/2} = 50 \text{ V}$$

- Find rms value of the waveform shown below



Solution

$$V_{\text{rms}} = \sqrt{\frac{1}{40} \left[\int_0^{t_1} v^2 dt + \int_{t_1}^{t_2} v^2 dt + \int_{t_2}^{40} v^2 dt \right]}$$

$$V_{\text{rms}} = \sqrt{\frac{1}{40} \left[\int_0^{10} v^2 dt + \int_{10}^{20} v^2 dt + \int_{20}^{40} v^2 dt \right]}$$

$$V_{\text{rms}} = \sqrt{\frac{1}{40} \left[\int_0^{10} 2500 dt + \int_{10}^{20} 0 dt + \int_{20}^{40} (5t - 150)^2 dt \right]}$$

Solution (contd)

$$V_{\text{rms}} = \sqrt{\frac{1}{40} \left[25000 + 0 + 16667 \right]}$$

$$V_{\text{rms}} = \sqrt{41667/40}$$

$$V_{\text{rms}} = 32.27 \text{ V}$$

This rounds off to $V_{\text{rms}} = 32 \text{ V}$

Average or d.c value

- The average value of an alternating current is expressed as
- **That steady current which transfers across any circuit the same charge as is transferred by that alternating current during the same time.**
- In the case of a symmetrical alternating current (i.e one whose two half cycles are similar , whether sinusoidal or non sinusoidal), the average value over a complete cycle is zero. So, in their case , the average value is obtained by adding or integrating the instantaneous values of current over one half-cycle. But in the case of an unsymmetrical ac (like half-wave rectified current) the average value must always be taken over the whole cycle.

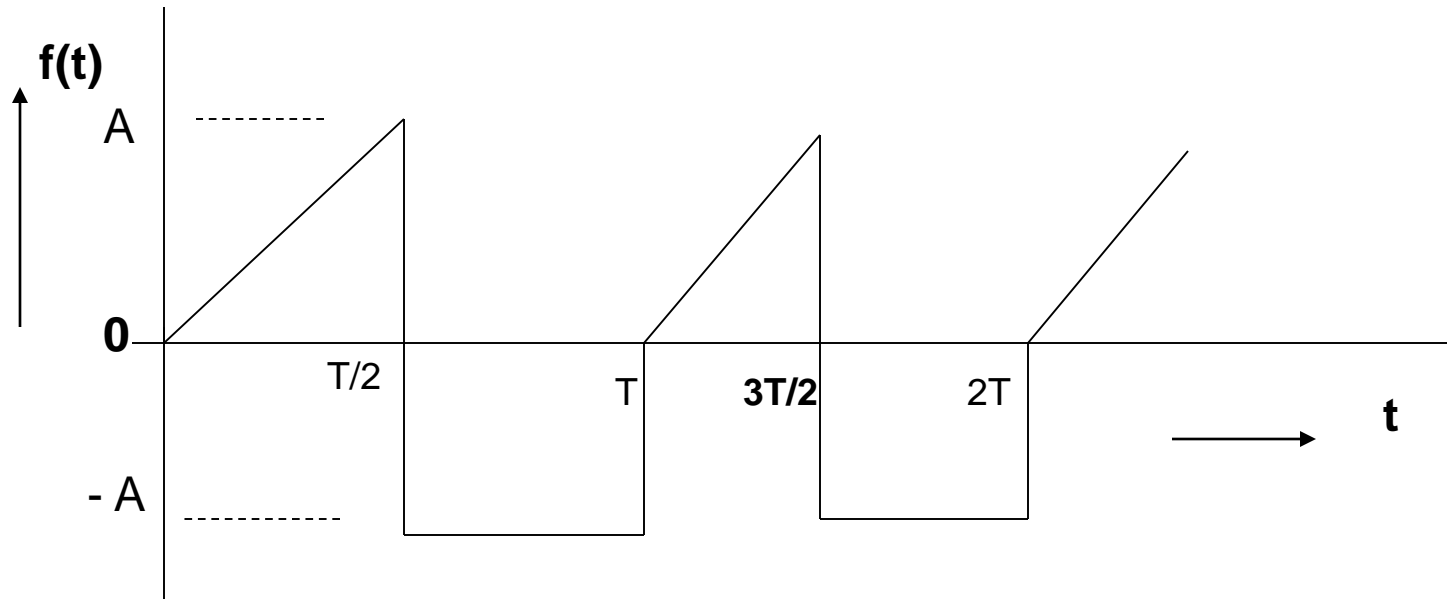
GENERAL DESCRIPTION OF SIGNALS (CONTD)

- **D-C Value** The d-c value (or average value) of a waveform has meaning only when the waveform is periodic . It is the average value of the waveform over one period

$$e_{d-c} = \frac{1}{T} \int_0^T e(t) dt \quad \text{where } T \text{ is the period .}$$

The d-c value of the wave form described earlier works out to be $-A/4$ v.

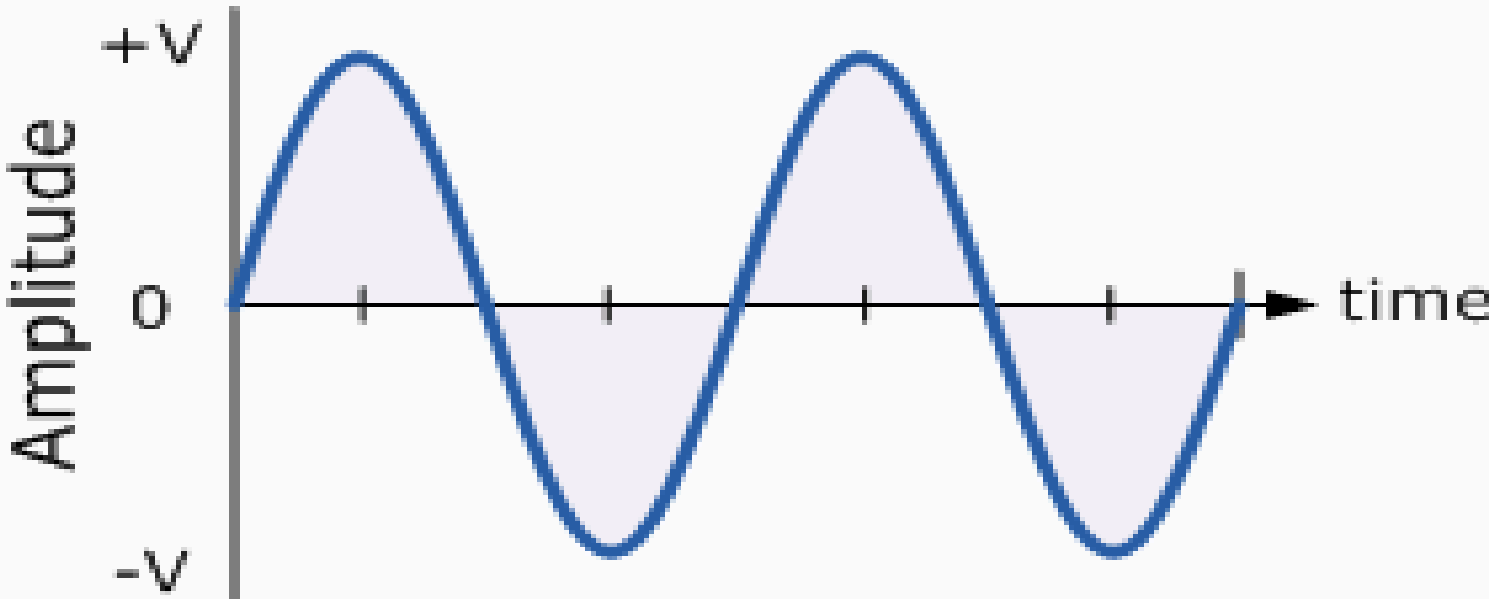
Ex : find average value of the waveform shown below

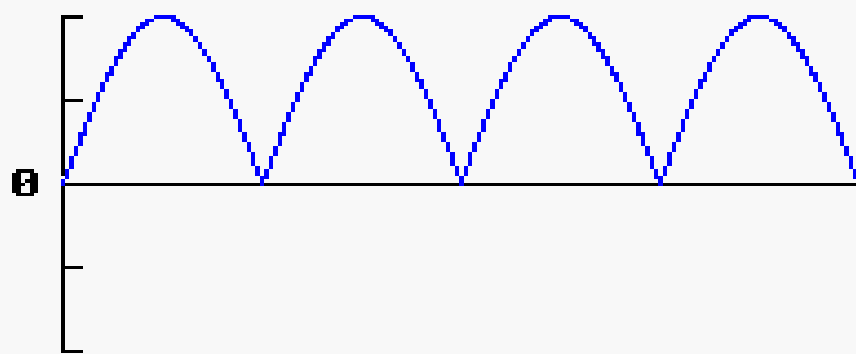
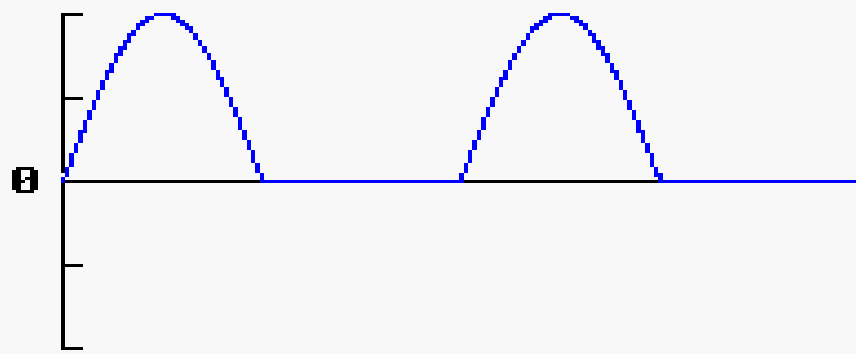
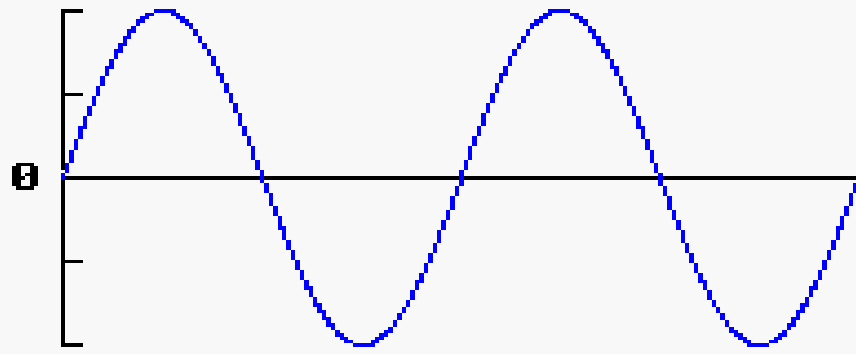


Solution

$$\begin{aligned} & T \\ \bullet \quad E_{dc} &= \frac{1}{T} \int_0^T e(t) dt \\ &= \frac{1}{T} \left[\int_0^{T/2} \left(\frac{2A}{T} \right) t dt + \int_{T/2}^T (-A) dt \right] \\ &= -A/4 \end{aligned}$$

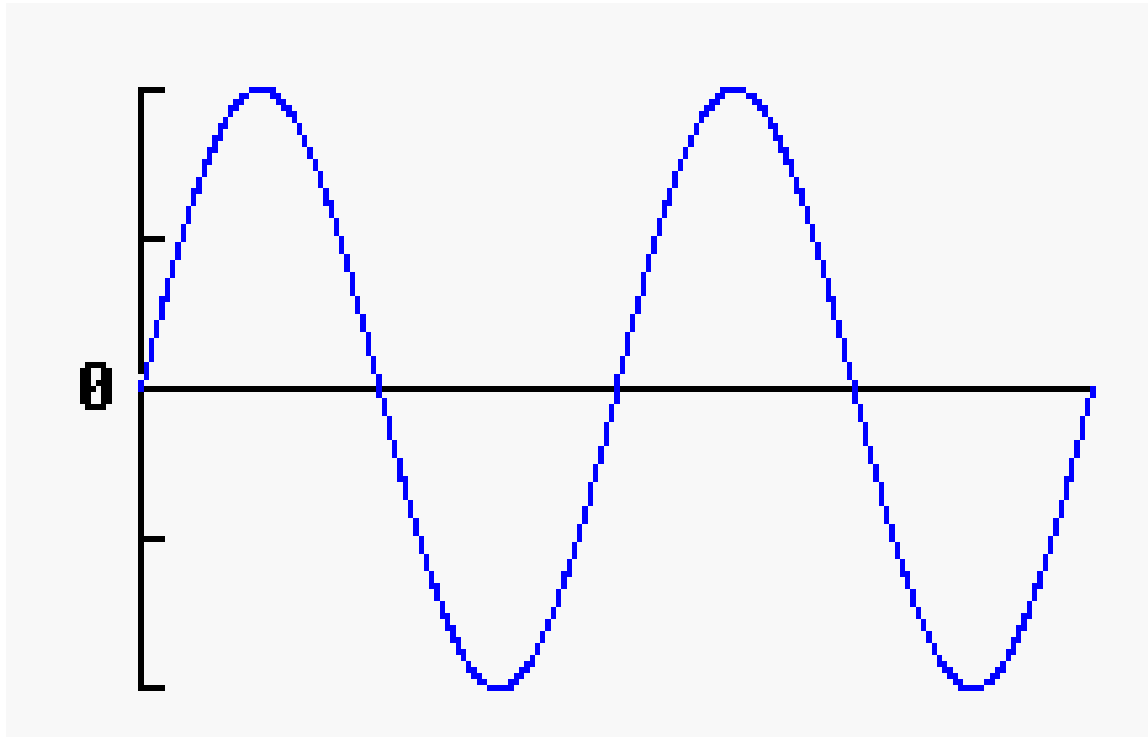
Sine wave





rms & average values of sine waves

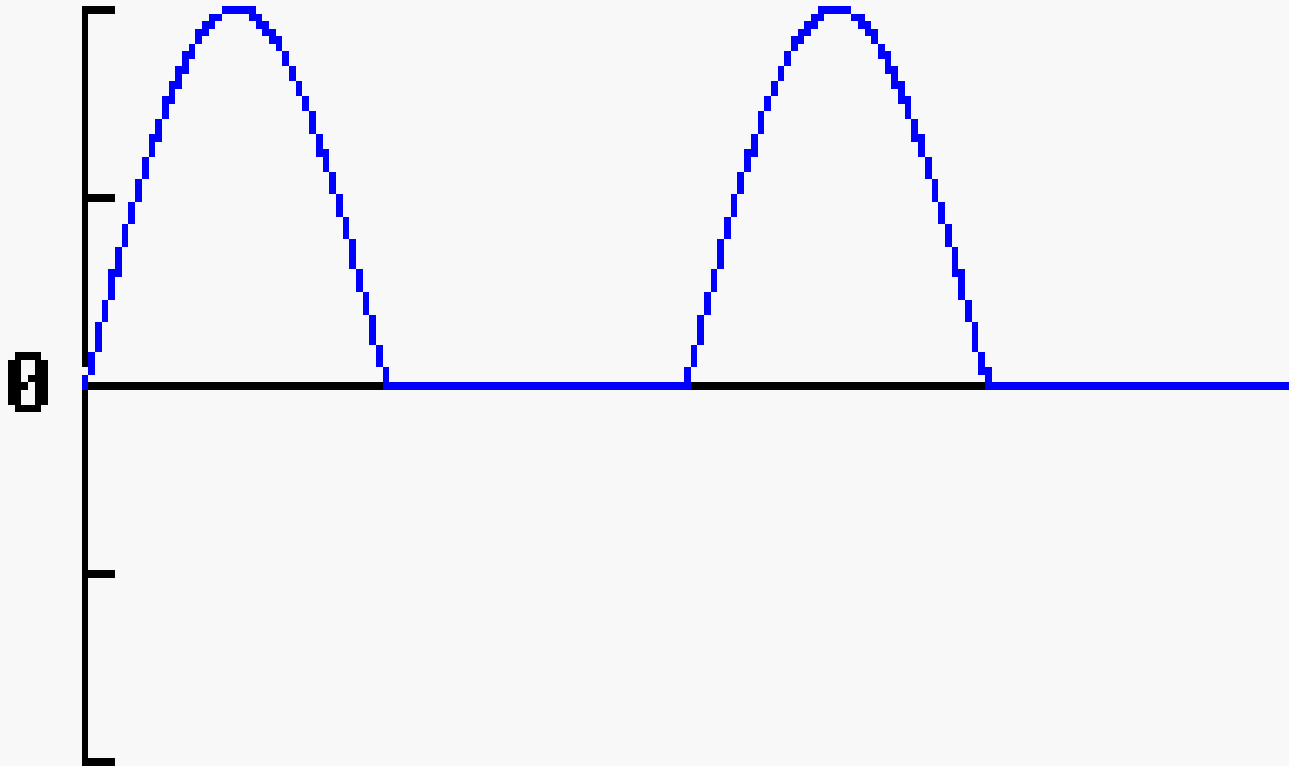
- $V = V_m \sin \omega t = V_m \sin \theta$



rms value = $V_m / \sqrt{2}$ average value = 0

rms & average values of sine waves

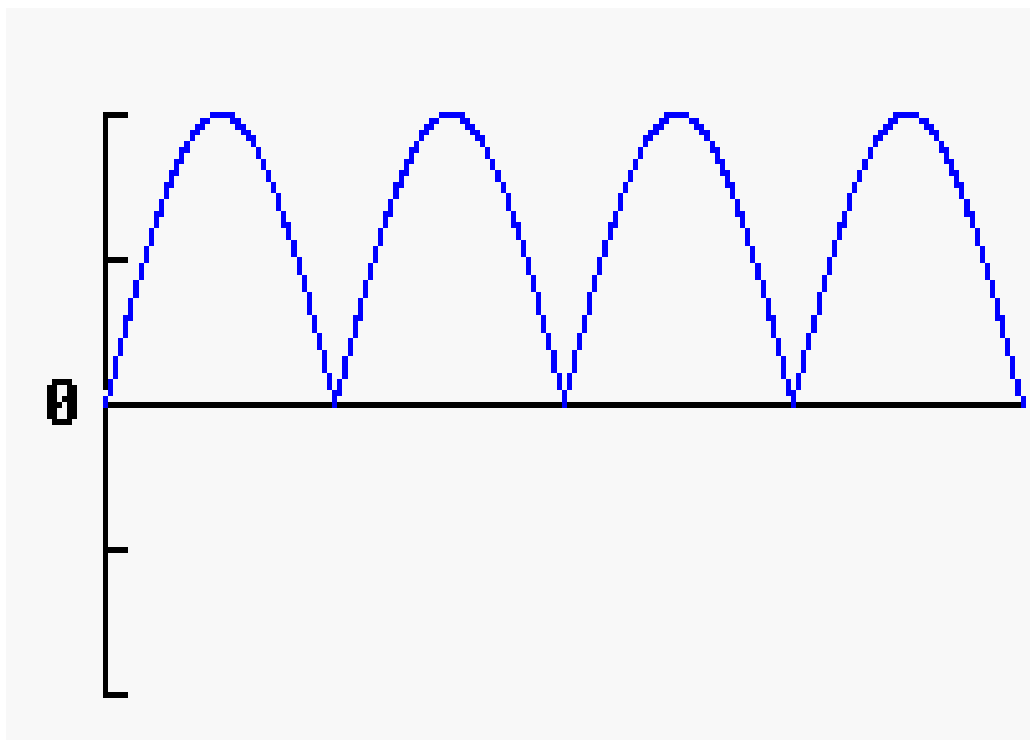
- $V = V_m \sin wt = V_m \sin \theta$



rms value = $V_m / 2$ average value = V_m / π

rms & average values of sine waves

- $V = V_m \sin \omega t = V_m \sin \theta$



rms value = $V_m / \sqrt{2}$

average value = $2 V_m / \pi$

GENERAL DESCRIPTION OF SIGNALS (CONTD)

- **DUTY CYCLE** The term Duty Cycle , D , is defined as the ratio of the time duration of the POSITIVE CYCLE t_o of a periodic waveform to the period ,T , that is

$$D = \frac{t_o}{T}$$

CREST FACTOR Crest factor is defined as the ratio of the peak voltage of the periodic waveform to the rms value (with the d-c component removed).

FORM FACTOR form factor is defined as the ratio of r.m.s value to average value of the waveform.